

Custom-designed hardware system with external trigger.

- **RGB camera:** High resolution rgb camera for capturing details in shape and appearance.
- Multispectral camera: Multi-channel camera in visible spectrum and near-infrared for capturing information in extended wavelength ranges.
- **Stero system:** Two grayscale cameras for depth perception.
- Halogen floodlights: For uniform illumination across the recorded area.
- Industrial PC: Recording unit capable to work in vibrating and temperature-critic environments.

An Intelligent Scanning Vehicle for Waste Collection Monitoring

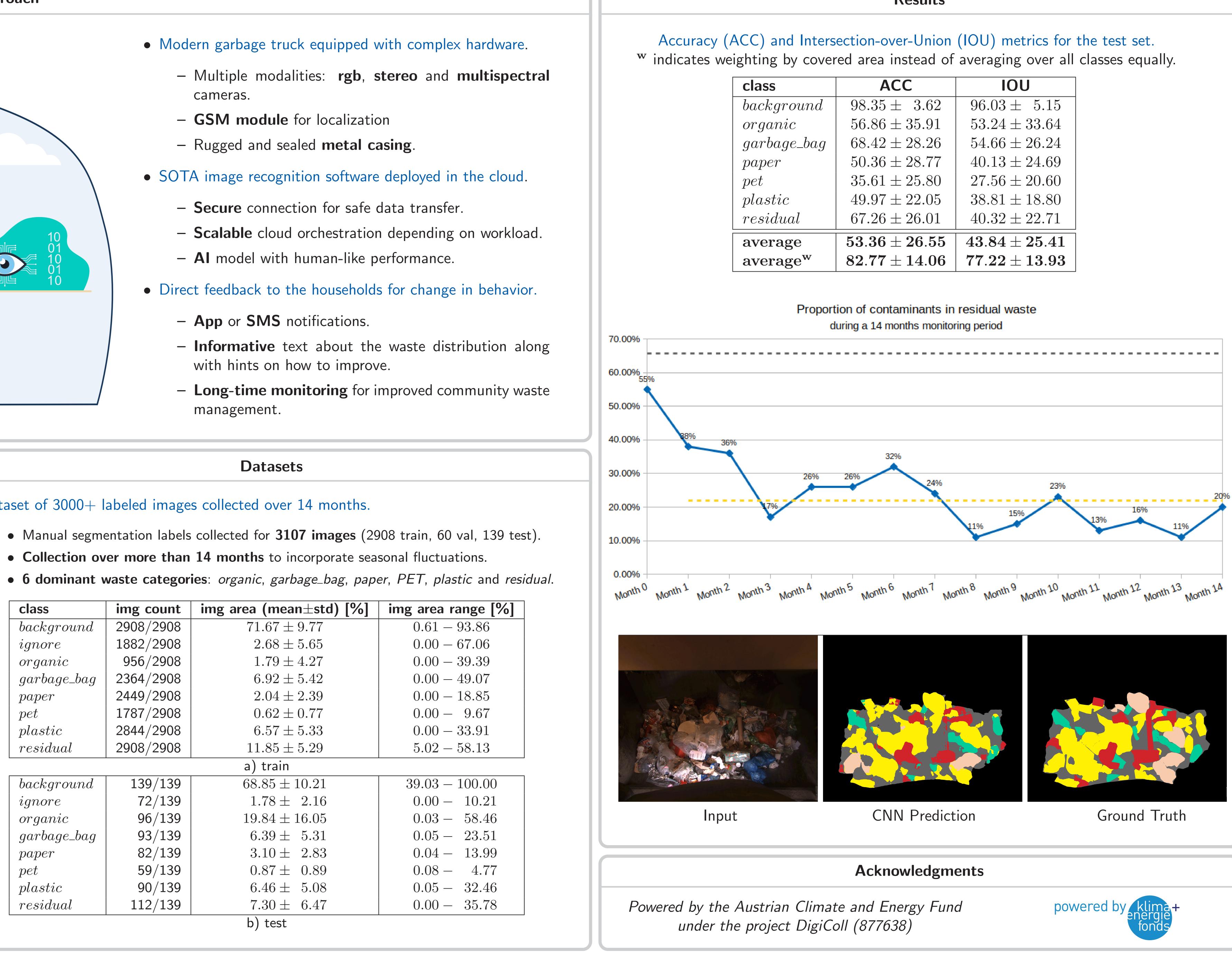
Georg Waltner¹, Malte Jaschik², Alfred Rinnhofer², Horst Possegger¹, Horst Bischof¹ {waltner, possegger, bischof}@icg.tugraz.at {malte.jaschik, alfred.rinnhofer}@joanneum.at ¹Institute of Computer Graphics and Vision (ICG), Graz University of Technology, Graz, Austria ²JOANNEUM RESEARCH Forschungsgesellschaft mbH, Graz, Austria

ower supply trigger unit

Dataset of 3000+ labeled images collected over 14 months.

- Collection over more than 14 months to incorporate seasonal fluctuations.

class	img count	img area (n
background	2908/2908	71.6
ignore	1882/2908	2.68
organic	956/2908	1.79
$garbage_bag$	2364/2908	6.92
paper	2449/2908	2.04
pet	1787/2908	0.62
plastic	2844/2908	6.5
residual	2908/2908	11.85
		a) tra
background	139/139	68.85
ignore	72/139	1.78
organic	96/139	19.84
$garbage_bag$	93/139	6.39
paper	82/139	3.10
pet	59/139	0.87
plastic	90/139	6.46
residual	112/139	7.30
		b) te







Results

ass	ACC	IOU
ckground	98.35 ± 3.62	96.03 ± 5.15
ganic	56.86 ± 35.91	53.24 ± 33.64
$rbage_bag$	68.42 ± 28.26	54.66 ± 26.24
per	50.36 ± 28.77	40.13 ± 24.69
t	35.61 ± 25.80	27.56 ± 20.60
astic	49.97 ± 22.05	38.81 ± 18.80
sidual	67.26 ± 26.01	40.32 ± 22.71
erage	$\textbf{53.36} \pm \textbf{26.55}$	$\textbf{43.84} \pm \textbf{25.41}$
rerage ^w	82.77 ± 14.06	$\textbf{77.22} \pm \textbf{13.93}$